AMENDMENTS TO THE SPECIFICATION

On page 25, lines 8 through 24, please amend the paragraph as follows:

--The designating range specification part 131 recognizes as the term for recognizing the location when the designator says "here". When the designator says "this one", the designating range specification part 131 recognizes as the term recognizing the object. When the designator says "here" and "this" or the like vaguely, the designating range specification part recognizes synonymously with "here" and "this one", and recognizes as the term (this way) showing the direction. Although the deciding method of the specific position is described below, when the position of an object Ta is decided as the specific position, an arrow [[vb_1]] $\underline{va_1}$ directing to the object Ta from the robot R, and an arrow va_2 directing to the object Ta from the designator M can be recognized as the direction designated by "this" or "this way". When the object is not particularly found, since the designator M designates the circumference vaguely, the specific position is the position of the designator M. The meaning of "this" or "this way" can be recognized as an arrow va_3 directing to the designator M.--

On page 26, lines 8 through 25, please amend the paragraph as follows:

--The designating range specification part 131 recognizes "there" as the term for recognizing the location when "there" is said. The designating range specification part 131 recognizes "that" as the term for recognizing the object when "that" is said. The designating range specification part 131 recognizes "that way" and "that one" or the like as being synonymous with "there" and "that", and recognizes as the term showing the direction. Although

the deciding method of the specific position is described below, when the positions of the object Tb_1 and object Tb_2 are decided as the specific position, an arrow vb_1 and arrow vb_2 directing to the object Tb_1 and the object [[Tb_1]] Tb_2 from Robot R, and an arrow [[vb_1]] vb_3 and arrow [[vb_2]] vb_4 directing to the object Tb_1 and the object [[Tb_1]] Tb_2 from the designator M can be recognized as the direction designated. When the object is not particularly found, the position distant to some extent vaguely is shown, and for example, the specific position may be recognized as the position of the robot R. In this case, the "that way" and "that one" can be recognized as an arrow vb_5 directing to the robot R.--